

# A Unified Framework for Semantic Matching in Architectural Floorplans

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# Introduction

- Floor plans images are 2D cross sections depicting relationships between rooms, spaces and other physical features at one level of a structure.
- Symbol spotting, room layout analysis have been solved as individual problems but a composite retrieval framework in floor plans does not exist.

#### Motivation

- Provide automatic lookup to retrieve similar past architectural projects to aid architects.
- Help property buyers to select floor plans with more specificity in terms of both room décor and layout.

#### Related Work

- Symbol spotting in graphical documents: Dutta et al. 2011, 2013
- Sketch based retrieval of architectural floor plans: Weber et al. 2013
- Room detection in architectural floor plans: Ahmed et al. 2012

# Stage 1: Segmentation Segmented I. Closing gaps at door locations. layout II. Floor plan boundary extraction. III. Dilation + erosion with unit radius structuring element. Morphological operation **Boundary extraction**

# Stage 3: Room Layout Matching

 $\overrightarrow{F_k} = (\lambda_k^{1}, \lambda_k^{2}, \lambda_k^{3}, \dots, \lambda_k^{n})^{T} \qquad \overrightarrow{x_k} = \phi^{T} \overrightarrow{F_k} = (x_k', x_k'', x_k''')^{T}$ 

 $d = \sqrt{\left(\overrightarrow{x_Q} - \overrightarrow{x_D}\right)^2}$ 

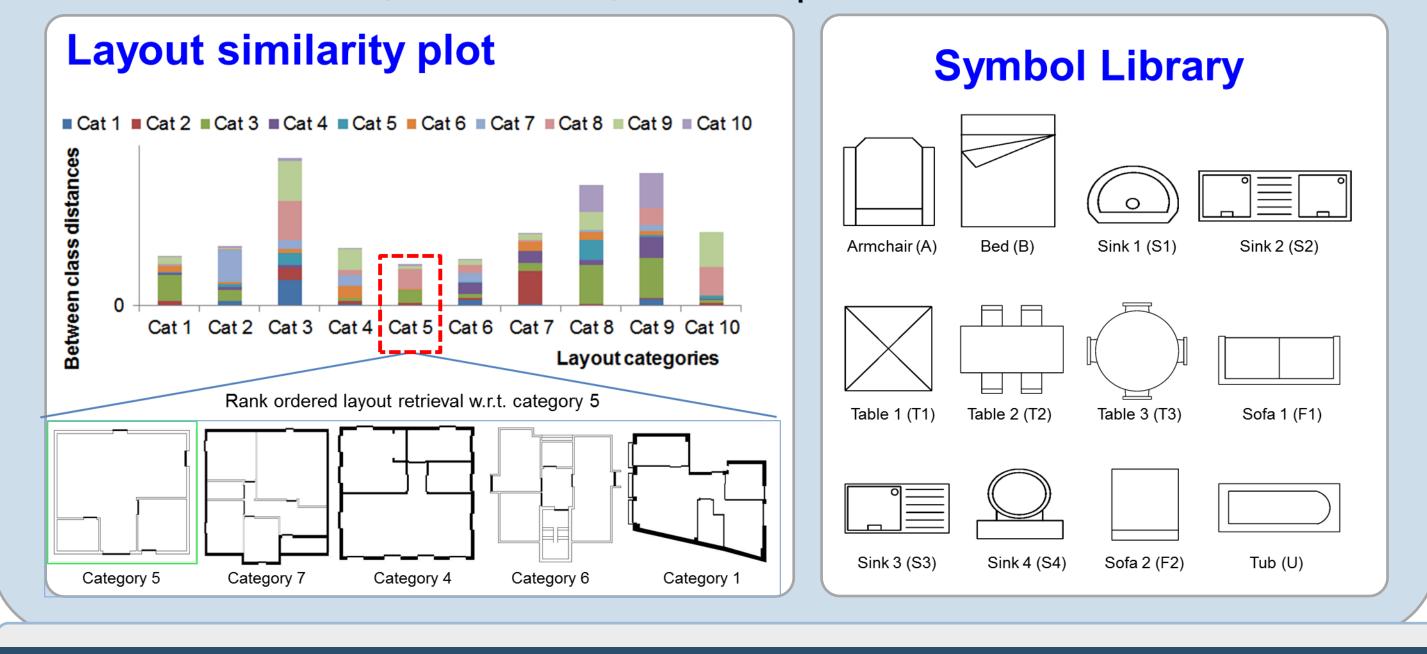
Leading 'n' eigen values as feature vector  $(\overrightarrow{F_k})$ 

through spectral embedding

> 3 - component vector > Similarity metric between query and database image feature vectors

## Experiments

On SESYD dataset, 10 classes, 100 samples/ class.



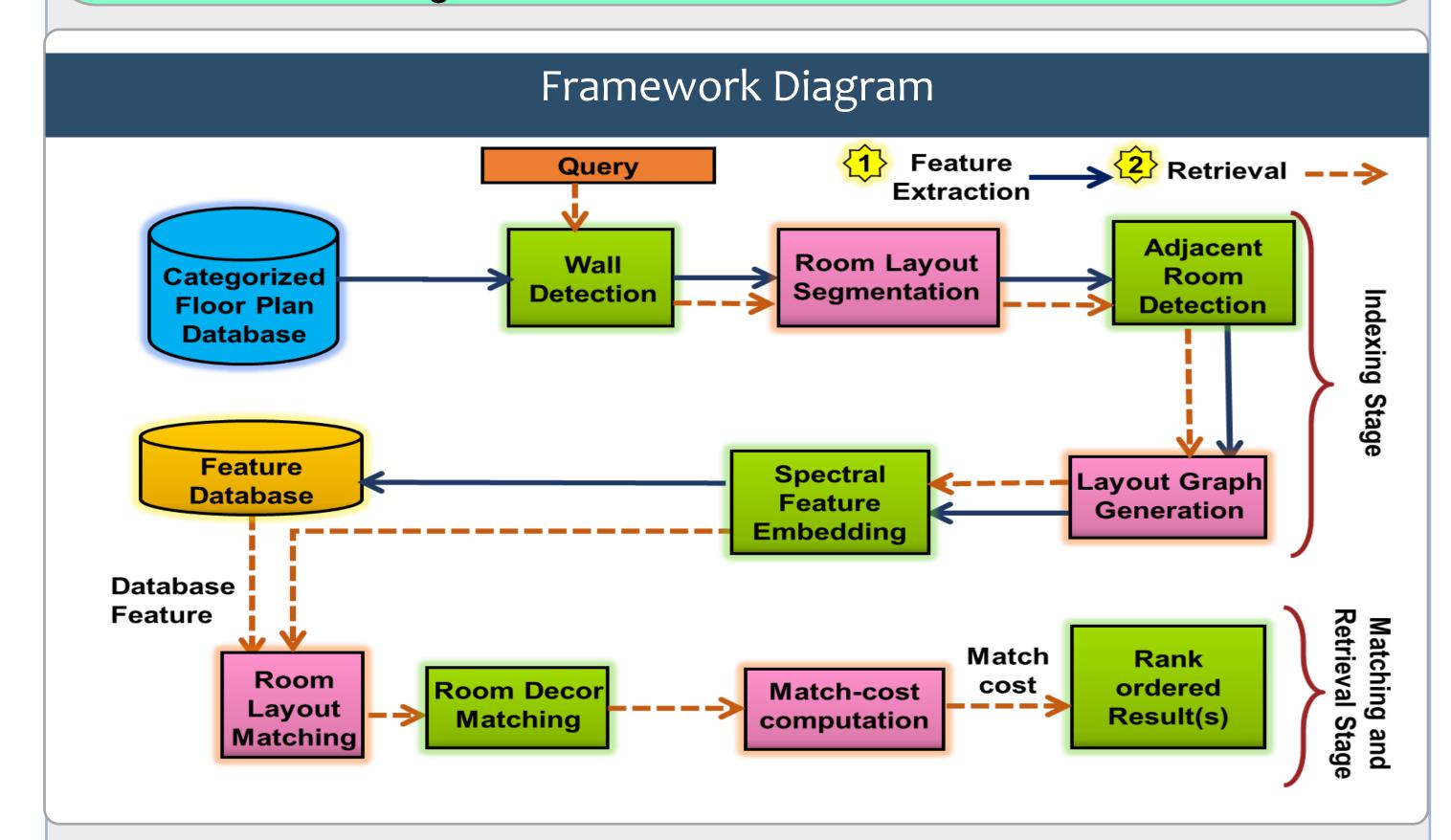
### Conclusions

# **Conclusions and Future Scope:**

- An inclusive framework considering structural and semantic similarity.
- A novel room décor matching algorithm for specificity while retrieval.
- Spectral embedding approach to represent layout graphs.
- Sketch based mode of query retrieval forms a future scope.

#### Contribution

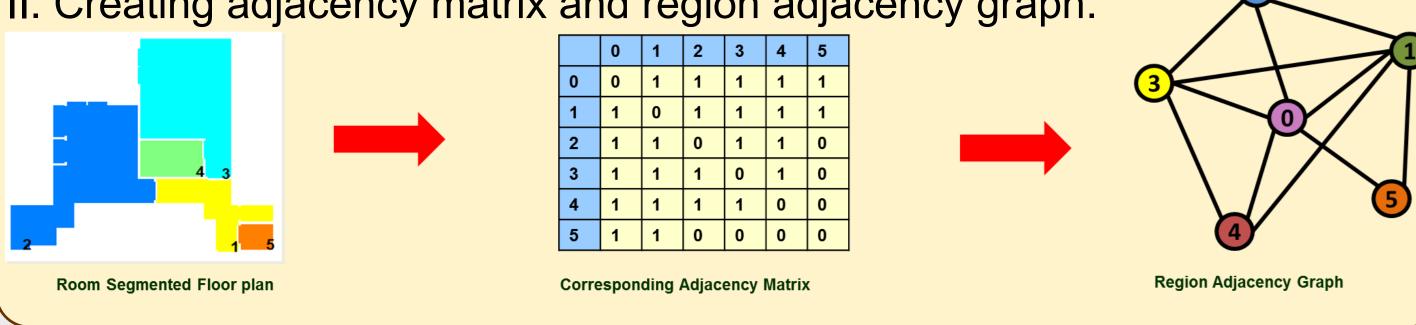
- Room segmentation and adjacent room detection algorithm to represent layouts as an undirected graph.
- Graph spectral embedding feature to uniquely represent floor plans for efficient matching.
- Two stage matching technique comprising both room layout matching and room décor matching.



### Stage 2: Room Adjacency Detection

I. Thresholding wall width and determining two-way adjacency in rooms.

II. Creating adjacency matrix and region adjacency graph.



### Stage 4: Room Décor Matching

- Detecting and categorizing furniture in the floor plan and initializing the matching cost.
- Adding a penalty matchcost if furniture count in two layouts not equal.
- Uniquely identifying furnitures in a layout and comparing type/ category of furniture in both layouts.
- Increment matchcost if furniture category matching, penalize otherwise.

